Complexity Analysis of the Lasso Regularization Path

Isoform Discovery from RNA-Seq Data

Julien Mairal, Inria, Grenoble

Statslab seminar, Cambridge, 2015



Collaborators



Bin Yu



Laurent Jacob

Jean-Philippe Vert

First part: a curiosity

• J. Mairal and B. Yu. Complexity Analysis of the Lasso Regularization Path. *Proc. ICML*. 2012.

Second part: a useful application of sparsity

• E. Bernard, L. Jacob, J. Mairal, and J-P. Vert. Efficient RNA Isoform Identification and Quantification from RNA-Seq Data with Network Flows. *Bioinformatics*. 2014.

Part I: Complexity Analysis of the Lasso Regularization Path

joint work with Bin Yu from UC Berkeley

• J. Mairal and B. Yu. Complexity Analysis of the Lasso Regularization Path. *Proc. ICML*. 2012.

Early thoughts about parsimony



(a) Dorothy Wrinch 1894–1980



(b) Harold Jeffreys 1891–1989

The existence of simple laws is, then, apparently, to be regarded as a quality of nature; and accordingly we may infer that it is justifiable to prefer a simple law to a more complex one that fits our observations slightly better.

[Wrinch and Jeffreys, 1921]. Philosophical Magazine Series.

Historical overview of parsimony

- 14th century: Ockham's razor;
- 1921: Wrinch and Jeffreys' simplicity principle;
- 1952: Markowitz's portfolio selection;
- 60 and 70's: best subset selection in statistics;
- 70's: use of the ℓ_1 -norm for signal recovery in geophysics;
- 90's: wavelet thresholding in signal processing;
- 1996: Olshausen and Field's dictionary learning;
- 1996–1999: Lasso (statistics) and basis pursuit (signal processing);
- 2006: compressed sensing (signal processing) and Lasso consistency (statistics);

What this work is about

• another paper about the Lasso/Basis Pursuit [Tibshirani, 1996, Chen et al., 1999]:

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$$\min_{\mathbf{w}\in\mathbb{R}^{p}}\frac{1}{2}\|\mathbf{y}-\mathbf{X}\mathbf{w}\|_{2}^{2}+\lambda\|\mathbf{w}\|_{1};$$
(1)

• the first complexity analysis of the homotopy method [Ritter, 1962, Osborne et al., 2000, Efron et al., 2004] for solving (1);

A story similar to

- the simplex algorithm for linear programs [Klee and Minty, 1972];
- the SVM regularization path [Gärtner, Jaggi, and Maria, 2010].

Regularizing with the ℓ_1 -norm



The projection onto a convex set is "biased" towards singularities.

Regularizing with the ℓ_2 -norm



The Lasso Regularization Path and the Homotopy

Under uniqueness assumption of the Lasso solution, the regularization path is piecewise linear:



Our Main Results

Theorem - worst case analysis

In the worst-case, the regularization path of the Lasso has exactly $(3^p + 1)/2$ linear segments.

Proposition - approximate analysis

There exists an ε -approximate path with $O(1/\sqrt{\varepsilon})$ linear segments.

Brief Introduction to the Homotopy Algorithm

Piecewise linearity

Under uniqueness assumptions of the Lasso solution, the regularization path $\lambda \mapsto \mathbf{w}^*(\lambda)$ is continuous and piecewise linear.

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Recipe of the homotopy method - main ideas

- **(**) finds a trivial solution $\mathbf{w}^*(\lambda_{\infty}) = 0$ with $\lambda_{\infty} = \|\mathbf{X}^\top \mathbf{y}\|_{\infty}$;
- Output the direction of the current linear segment of the path;
- **③** follow the direction of the path by decreasing λ ;
- stop at the next "kink" and go back to 2.

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Caveats

- kinks can be very close to each other;
- the direction of the path can involve ill-conditioned matrices;
- worst-case exponential complexity (main result of this work).

Theorem - worst case analysis

In the worst-case, the regularization path of the Lasso has exactly $(3^p + 1)/2$ linear segments.



Regularization path, p=6

Consider a Lasso problem $(\mathbf{y} \in \mathbb{R}^n, \mathbf{X} \in \mathbb{R}^{n \times p})$. Define the vector $\tilde{\mathbf{y}}$ in \mathbb{R}^{n+1} and the matrix $\tilde{\mathbf{X}}$ in $\mathbb{R}^{(n+1) \times (p+1)}$ as follows:

$$\tilde{\mathbf{y}} \triangleq \begin{bmatrix} \mathbf{y} \\ y_{n+1} \end{bmatrix}, \quad \tilde{\mathbf{X}} \triangleq \begin{bmatrix} \mathbf{X} & 2\alpha \mathbf{y} \\ \mathbf{0} & \alpha y_{n+1} \end{bmatrix},$$

where $y_{n+1} \neq 0$ and $0 < \alpha < \lambda_1/(2\mathbf{y}^\top \mathbf{y} + y_{n+1}^2)$.

Adverserial strategy

If the regularization path of the Lasso (\mathbf{y}, \mathbf{X}) has k linear segments, the path of $(\tilde{\mathbf{y}}, \tilde{\mathbf{X}})$ has 3k - 1 linear segments.

$$\tilde{\mathbf{y}} \triangleq \begin{bmatrix} \mathbf{y} \\ y_{n+1} \end{bmatrix}, \quad \tilde{\mathbf{X}} \triangleq \begin{bmatrix} \mathbf{X} & 2\alpha \mathbf{y} \\ 0 & \alpha y_{n+1} \end{bmatrix},$$

Let us denote by $\{\eta^1, \ldots, \eta^k\}$ the sequence of k sparsity patterns in $\{-1, 0, 1\}^p$ encountered along the path of the Lasso (\mathbf{y}, \mathbf{X}) .

The new sequence of sparsity patterns for $(\mathbf{\tilde{y}}, \mathbf{\tilde{X}})$ is



We are now in shape to build a pathological path with $(3^p + 1)/2$ linear segments. Note that this lower-bound complexity is tight.

$$\mathbf{y} \triangleq \begin{bmatrix} 1\\1\\1\\\vdots\\1 \end{bmatrix}, \quad \mathbf{X} \triangleq \begin{bmatrix} \alpha_1 & 2\alpha_2 & 2\alpha_3 & \dots & 2\alpha_p\\ 0 & \alpha_2 & 2\alpha_3 & \dots & 2\alpha_p\\ 0 & 0 & \alpha_3 & \dots & 2\alpha_p\\\vdots & \vdots & \vdots & \ddots & \vdots\\ 0 & 0 & 0 & \dots & \alpha_p \end{bmatrix},$$

Refinement of Giesen, Jaggi, and Laue [2010] for the Lasso

Strong Duality



Strong duality means that $\max_{\kappa} g(\kappa) = \min_{\mathbf{w}} f(\mathbf{w})$

Duality Gaps



Strong duality means that $\max_{\kappa} g(\kappa) = \min_{\mathbf{w}} f(\mathbf{w})$

The duality gap guarantees us that $0 \leq f(\mathbf{\tilde{w}}) - f(\mathbf{w}^{\star}) \leq \delta(\mathbf{\tilde{w}}, \mathbf{\tilde{\kappa}}).$

$$\begin{split} \min_{\mathbf{w}} \Big\{ f_{\lambda}(\mathbf{w}) \stackrel{\scriptscriptstyle \Delta}{=} \frac{1}{2} \|\mathbf{y} - \mathbf{X}\mathbf{w}\|_{2}^{2} + \lambda \|\mathbf{w}\|_{1} \Big\}, \qquad (\text{primal}) \\ \max_{\kappa} \Big\{ g_{\lambda}(\kappa) \stackrel{\scriptscriptstyle \Delta}{=} -\frac{1}{2} \kappa^{\top} \kappa - \kappa^{\top} \mathbf{y} \quad \text{s.t.} \quad \|\mathbf{X}^{\top} \kappa\|_{\infty} \leq \lambda \Big\}. \qquad (\text{dual}) \end{split}$$

$\varepsilon\text{-approximate solution}$

w satisfies $APPROX_{\lambda}(\varepsilon)$ when there exists a dual variable κ s.t.

$$\delta_{\lambda}(\mathbf{w}, \mathbf{\kappa}) = f_{\lambda}(\mathbf{w}) - g_{\lambda}(\mathbf{\kappa}) \leq \varepsilon f_{\lambda}(\mathbf{w}).$$

ε -approximate path

A path $\mathcal{P} : \lambda \mapsto \mathbf{w}(\lambda)$ is an approximate path if it always contains ε -approximate solutions.

(see Giesen et al. [2010] for generic results on approximate paths)

Main relation

$$APPROX_{\lambda}(0) \Longrightarrow APPROX_{\lambda(1-\sqrt{\varepsilon})}(\varepsilon)$$

Key: find an appropriate dual variable $\kappa(\mathbf{w})$ + simple calculation; Proposition - approximate analysis there exists an ε -approximate path with at most $\left\lceil \frac{\log(\lambda_{\infty}/\lambda_{1})}{\sqrt{\varepsilon}} \right\rceil$ segments.

Approximate homotopy - main ideas

- Maintain approximate optimality conditions along the path;
- Make steps in λ greater than or equal to $\lambda(1 \theta\sqrt{\varepsilon})$;
- When the kinks are too close to each other, make a large step and switch to first-order method;

A Few Messages to Conclude

- Despite its exponential complexity, the homotopy algorithm remains extremely powerful in practice;
- numerical stability is still an issue of the homotopy algorithm;
- when one does not care about precision, the worst-case complexity of the path can be significantly reduced.

Part II: Isoform Discovery from RNA-Seq Data with Network Flows

joint work with **Elsa Bernard** (Institut Curie), Laurent Jacob (CNRS) and Jean-Philippe Vert (Institut Curie)

• E. Bernard, L. Jacob, J. Mairal, and J-P. Vert. Efficient RNA Isoform Identification and Quantification from RNA-Seq Data with Network Flows. *Bioinformatics*. 2014.

DNA Transcription/Translation (Central Dogma, 1958)



Modern Biology and Challenges



DOE Joint Genome institute

- biology is producing massive amount of data;
- sequencing one genome now costs about 1000\$ (vs 0.1 billion \$ in 2001), and produces about a few gigabytes of data;
- prediction from DNA data.

Alternative Splicing: 1 Gene = Many Proteins



In human, 28k genes give 120k known transcripts (Pal et al., 2012)

Importance of Alternative Splicing



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Opportunities for Drug Developments...



(*Pal et al., 2012*)

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RNA-Seq or Next-Generation Sequencing

What is RNA-Seq?

• RNA-Seq measures abundance of RNA;



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The Isoform Identification and Quantification Problem



Given a biological sample can we:

- identify the isoform(s) of each gene present in the sample?
- Quantify their abundance?

From RNA-Seq Reads to Isoforms



De Novo methods



Genome-Based Methods



Genome-Based Isoforms Reconstruction



Place in the literature



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Contributions

- NO NEED for FILTERING of candidate isoforms
- FASTER than existing methods that solve the same problem

flow method

- adapted to LONG READS
- R package
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Contributions





Home » Bioconductor 2.13 » Software Packages » flipflop

flipflop

Fast lasso-based isoform prediction as a flow problem

Bioconductor version: Release (2.13)

Flipflop discovers which isoforms of a gene are expressed in a given sample together with their abundances, based on RNA-Seq read data.

Author: Elsa Bernard, Laurent Jacob, Julien Mairal and Jean-Philippe Vert

Maintainer: Elsa Bernard <elsa.bernard at mines-paristech.fr>

To install this package, start R and enter:

source("http://bioconductor.org/biocLite.R")
biocLite("flipflop")

Isoforms are Paths in a Graph

• Splicing graph for a gene with 5 exons:



• FlipFlop graph: 1 type of read \leftrightarrow 1 node



























• Splicing graph for a gene with 5 exons:



• FlipFlop graph: one path with abundance β_1







Select a Small Number of Paths?

$n \text{ exons} \rightarrow \sim 2^n \text{ paths/candidate isoforms}$

feature selection problem with \sim 1000 candidates for 10 exons and \sim 1000000 for 20 exons

Minimal path cover

Cufflinks

Regularization approach

 IsoLasso, NSMAP, SLIDE, iReckon, MiTie, FlipFlop

Select a Small Number of Paths?

Cufflinks strategy

A two-step approach

- find a set of *minimal paths* to explain read positions (independent from read counts)
- estimate isoform abundances using read counts

Select a small number of paths?

Regularization approach

- Suppose there are *c* candidate isoforms (c large)
- **2** Let β the unknown c-dimensional vector of abundance

Select a small number of paths?

Regularization approach

- Suppose there are c candidate isoforms (c large)
- **2** Let β the unknown c-dimensional vector of abundance
- Let L(β) quantify whether β explains the observed read counts
 e.g., Poisson negative log-likelihood:

$$\mathcal{L}(oldsymbol{eta}) = \sum_{\mathsf{node } u} -\log p(X_u) \; \; \mathsf{with} \; \; X_u \sim \mathcal{P}(\delta_u) \; \; \mathsf{and} \; \; \delta_u \propto l_u \; \sum_{\mathsf{path } p \ni u} oldsymbol{eta}_p$$

Select a small number of paths?

Regularization approach

- Suppose there are c candidate isoforms (c large)
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Regularization-based approaches try to solve:

$$\min_{eta \in \mathbb{R}^c_+} \mathcal{L}(eta)$$
 such that eta is sparse

Isoform Deconvolution with the ℓ_1 -norm

 $\ell_1\text{-}\mathsf{regularization}$

Estimate β sparse by solving:

 $\min_{\boldsymbol{\beta} \in \mathbb{R}_+^c} \mathcal{L}(\boldsymbol{\beta}) + \lambda \| \boldsymbol{\beta} \|_1 \,\,,$

with $\ensuremath{\mathcal{L}}$ a convex loss function.

Computationally challenging:

- \rightarrow IsoLasso: strong filtering
- \rightarrow NSMAP, SLIDE: number of exons cut-off

FlipFlop: Fast Lasso-based Isoform Prediction as a FLOw Problem

- \rightarrow no filtering
- \rightarrow no exons restrictions

Fast Isoform Deconvolution with the lasso

Theoretical (practical) result

The isoform deconvolution problem

$$\min_{\boldsymbol{\beta} \in \mathbb{R}^{c}_{+}} \mathcal{L}(\boldsymbol{\beta}) + \lambda \|\boldsymbol{\beta}\|_{1} ,$$

can be solved in **polynomial time** with the number of nodes of the splicing graph.

Ideas:

- **()** the sum of isoform abundances correspond to a **flow** on the graph
- reformulation as a convex cost flow problem (Mairal and Yu, 2012)
- recover isoforms by flow decomposition algorithm

Combinations of isoforms are flows



Flux Capacitor. 2008. A Novel Min-Cost Flow Method for Estimating Transcript Expression with RNA-Seq. RECOMB-2013.

Equivalent flow problem (simpler!)



• For each edge sum abundances of isoforms that include the edge :

$$f_{uv} = \sum_{\text{path } p
ightarrow (u,v)} eta_p \quad \text{is a flow}$$

Moreover

$$\|\boldsymbol{\beta}\|_1 = \sum_{\text{path } p} \boldsymbol{\beta}_p = f_t$$

Therefore

$$\min_{\beta \in \mathbb{R}_+^c} \mathcal{L}(\beta) + \lambda \|\beta\|_1 \text{ is equivalent to } \min_{\substack{\mathbf{f} \text{ flow}}} \tilde{\mathcal{L}}(\mathbf{f}) + \lambda \mathbf{f}_{\mathbf{t}}$$

Technical details

Poisson Loss (with binary matrix **U**):

$$\mathcal{L}(\mathbf{U}^{\mathsf{T}}\boldsymbol{\beta}) = \sum_{u \in V} \left[\mathsf{N} \mathsf{I}_u (\mathbf{U}^{\mathsf{T}}\boldsymbol{\beta})_u - \mathbf{y}_u \log(\mathsf{N} \mathsf{I}_u (\mathbf{U}^{\mathsf{T}}\boldsymbol{\beta})_u) \right]$$

Flow Decomposition:

$$f_{uv} = \sum_{p \in \mathcal{P}'} \beta_p \mathbf{1}_{\{(u,v) \in p\}}$$
$$\Rightarrow f_v = \sum_{u \in V'} f_{uv} = (\mathbf{U}^T \beta)_v$$

Convex Cost Flow:

$$\min_{f \text{flow}} \sum_{u \in V} [NI_u f_u - \mathbf{y}_u \log(f_u)] + \lambda f_u$$

Solved using ε -relaxation method (Bertsekas 1998).

Summary

Isoform Detection=Path Selection Problem

 $\sim 2^n$ variables (all paths in the splicing graph)

Equivalent Network Flow Problem

 $\sim rac{n^2}{2}$ variables (all exons and exon-exon junctions in the splicing graph)

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Network Flow Algorithms

Efficient Algorithms ! Polynomial Time.

Performance increases with read length

- Human Simulation: hg19, 1137 genes on chr1, 1million reads by transcript levels.
- Simulator: http://alumni.cs.ucr.edu/~liw/rnaseqreadsimulator.html



Performance increases with coverage

- Human Simulation: hg19, 1137 genes on chr1, 1million reads by transcript levels.
- Simulator: http://alumni.cs.ucr.edu/~liw/rnaseqreadsimulator.html



Extension to paired-end reads

- Human Simulation: hg19, 1137 genes on chr1, 1 million reads by transcript levels.
- Simulator: http://alumni.cs.ucr.edu/~liw/rnaseqreadsimulator.html



Speed Trial

۲ Human Simulation: hg19, 1137 genes on chr1, 1 million reads by transcript levels. ۲

Simulator: http://alumni.cs.ucr.edu/~liw/rnasegreadsimulator.html





Julien Mairal, Inria

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GC bias - Precision-Recall curve

Human Simulation: hg19, chr1, 150bp single-end reads, 2 million, 4140 transcripts.

FluxSimulator, Griebel et al, 2012.

Model selection: set of solutions minimizing $\mathcal{L}(\beta) + \lambda \|\beta\|_1$ for different values of $\lambda \to \text{BIC}$ criteria



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Real Data

Human: 50 million 75bp paired-end reads.



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Conclusion/Discussion

 $\mathsf{FlipFlop} \to \mathsf{transcripts}$ reconstruction over an exponential number of candidates in polynomial time

- In the second second
- **Omega Solution:** Cross Validation, Stability Selection?
- Multiple-samples: on-going work with promising preliminary results.
- Oifferential Expression testing at the isoform level ?

Conclusion/Discussion: get FlipFlop for free!



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Advertisement: free monographs

J. Mairal, F. Bach and J. Ponce. *Sparse Modeling* for *Image and Vision Processing*. Foundations and Trends in Computer Graphics and Vision. 2014.





Optimization with Sparsity-Inducing Penalties

Francis Bach, Rodolphe Jenatton, Julien Mairal and Guillaume Obozinski

new

F. Bach, R. Jenatton, J. Mairal, and G. Obozinski. *Optimization with sparsity-inducing penalties.* Foundations and Trends in Machine Learning, 4(1). 2012.

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Advertisement SPAMS toolbox (open-source)

- C++ interfaced with Matlab, R, Python.
- proximal gradient methods for l₀, l₁, elastic-net, fused-Lasso, group-Lasso, tree group-Lasso, tree-l₀, sparse group Lasso, overlapping group Lasso...
- ...for square, logistic, multi-class logistic loss functions.
- handles sparse matrices, provides duality gaps.
- fast implementations of OMP and LARS homotopy.
- dictionary learning and matrix factorization (NMF, sparse PCA).
- coordinate descent, block coordinate descent algorithms.
- fast projections onto some convex sets.

Try it! http://www.di.ens.fr/willow/SPAMS/

References

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Precision-Recall curves on real data



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Speed comparison on real data



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Stability study



Human Simulation: Abundances

hg19, 1137 genes on chr1, 1million 75 bp single-end reads by transcript levels.



Simulation: Deviation

hg19, 1137 genes on chr1, 1million 75 bp single-end reads by transcript levels.



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Worst case analysis - Backup Slide

$$\tilde{\mathbf{y}} \triangleq \begin{bmatrix} \mathbf{y} \\ y_{n+1} \end{bmatrix}, \quad \tilde{\mathbf{X}} \triangleq \begin{bmatrix} \mathbf{X} & 2\alpha \mathbf{y} \\ 0 & \alpha y_{n+1} \end{bmatrix},$$

Some intuition about the adverserial strategy:

- **()** the patterns of the new path must be $[\boldsymbol{\eta}^{i op},0]^ op$ or $[\pm \boldsymbol{\eta}^{i op},1]^ op;$
- **2** the factor α ensures the (p + 1)-th variable to enter late the path;
- **③** after the *k* first kinks, we have $\mathbf{y} \approx \mathbf{X}\mathbf{w}^{\star}(\lambda)$ and thus

$$\tilde{\mathbf{X}} \begin{bmatrix} \mathbf{w}^{\star}(\lambda) \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ y_{n+1} \end{bmatrix} \approx \tilde{\mathbf{y}} \approx \tilde{\mathbf{X}} \begin{bmatrix} -\mathbf{w}^{\star}(\lambda) \\ 1/\alpha \end{bmatrix}$$

Worst case analysis - Backup Slide 2

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$$\begin{split} \min_{\tilde{\mathbf{w}}\in\mathbb{R}^{p},\tilde{w}\in\mathbb{R}} \frac{1}{2} \left\| \tilde{\mathbf{y}} - \tilde{\mathbf{X}} \begin{bmatrix} \tilde{\mathbf{w}} \\ \tilde{w} \end{bmatrix} \right\|_{2}^{2} + \lambda \left\| \begin{bmatrix} \tilde{\mathbf{w}} \\ \tilde{w} \end{bmatrix} \right\|_{1}^{2} =,\\ \min_{\tilde{\mathbf{w}}\in\mathbb{R}^{p},\tilde{w}\in\mathbb{R}} \frac{1}{2} \| (1 - 2\alpha\tilde{w})\mathbf{y} - \mathbf{X}\tilde{\mathbf{w}} \|_{2}^{2} + \frac{1}{2} (y_{n+1} - \alpha y_{n+1}\tilde{w})^{2} + \lambda \|\tilde{\mathbf{w}}\|_{1} + \lambda |\tilde{w}|. \end{split}$$

is equivalent to

$$\min_{\tilde{\mathbf{w}}' \in \mathbb{R}^p} \frac{1}{2} \|\mathbf{y} - \mathbf{X} \tilde{\mathbf{w}}'\|_2^2 + \frac{\lambda}{|1 - 2\alpha \tilde{\mathbf{w}}^*|} \|\tilde{\mathbf{w}}'\|_1,$$

and then

$$\tilde{\mathbf{w}}^{\star} = \begin{cases} (1 - 2\alpha \tilde{w}^{\star}) \mathbf{w}^{\star} \left(\frac{\lambda}{|1 - 2\alpha \tilde{w}^{\star}|}\right) & \text{ if } \tilde{w}^{\star} \neq \frac{1}{2\alpha} \\ 0 & \text{ otherwise } \end{cases}$$

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